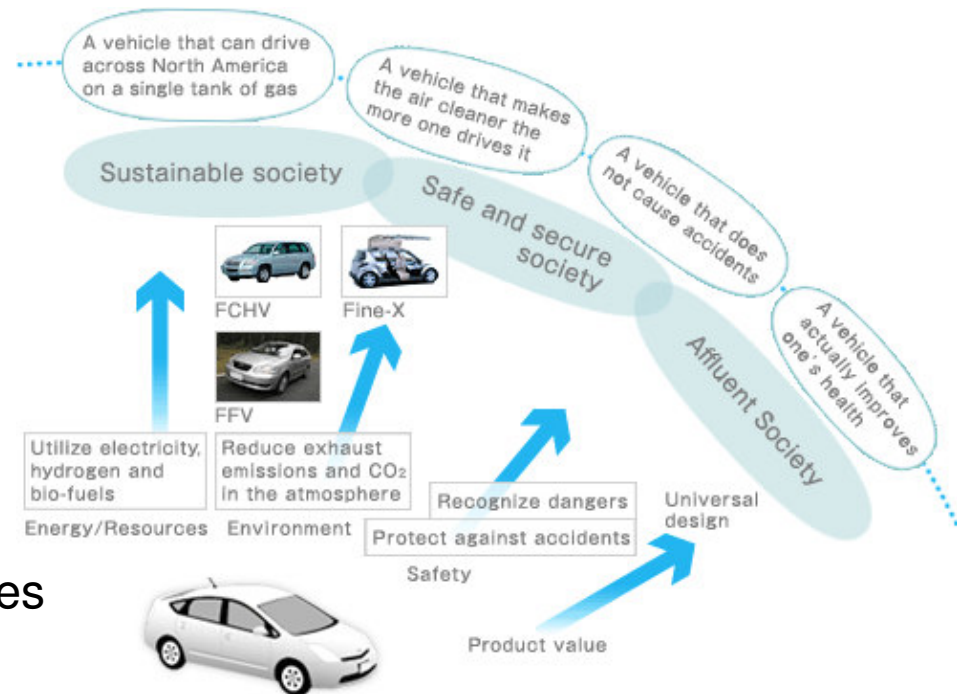
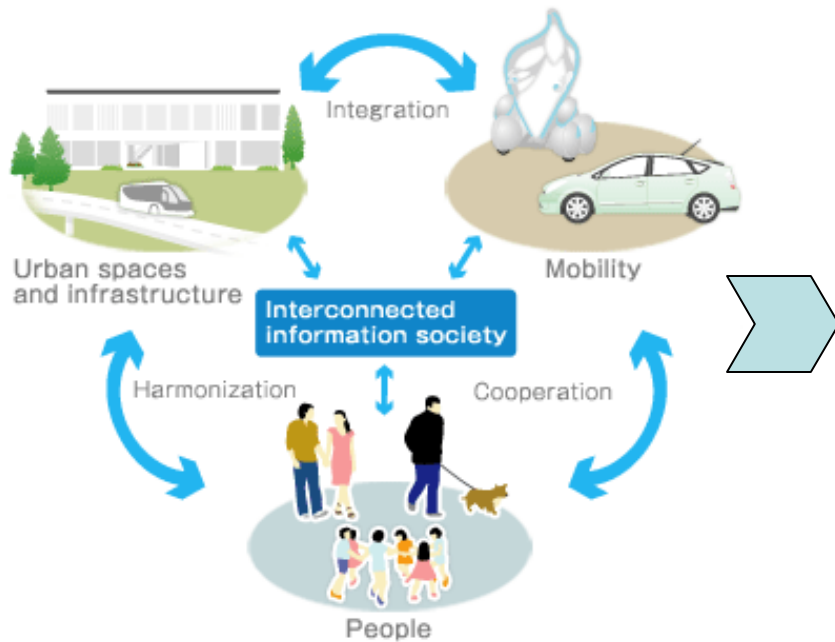


# Control, Electronics, Communication, and Embedded Software

## Infrastructure integration

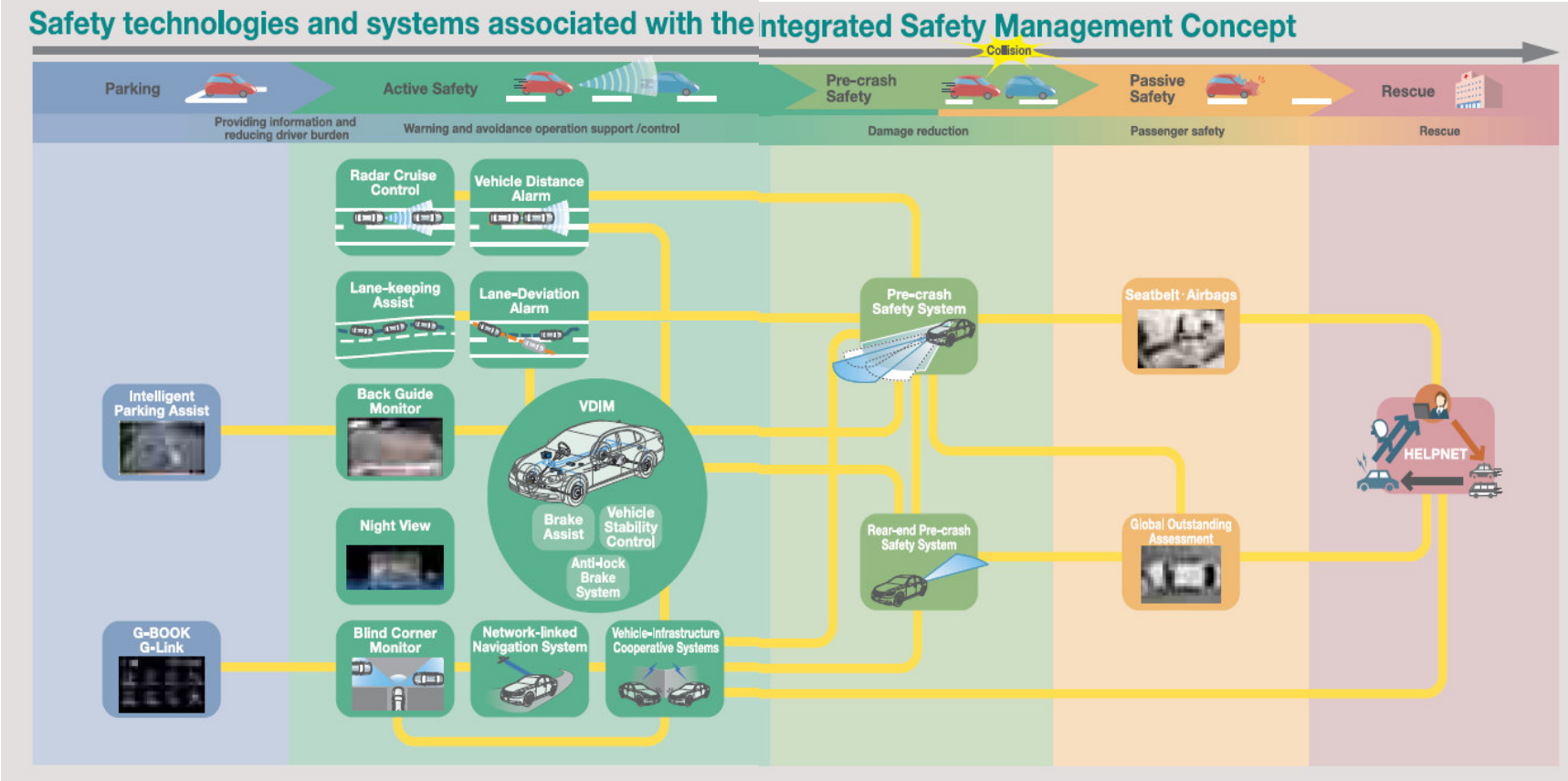
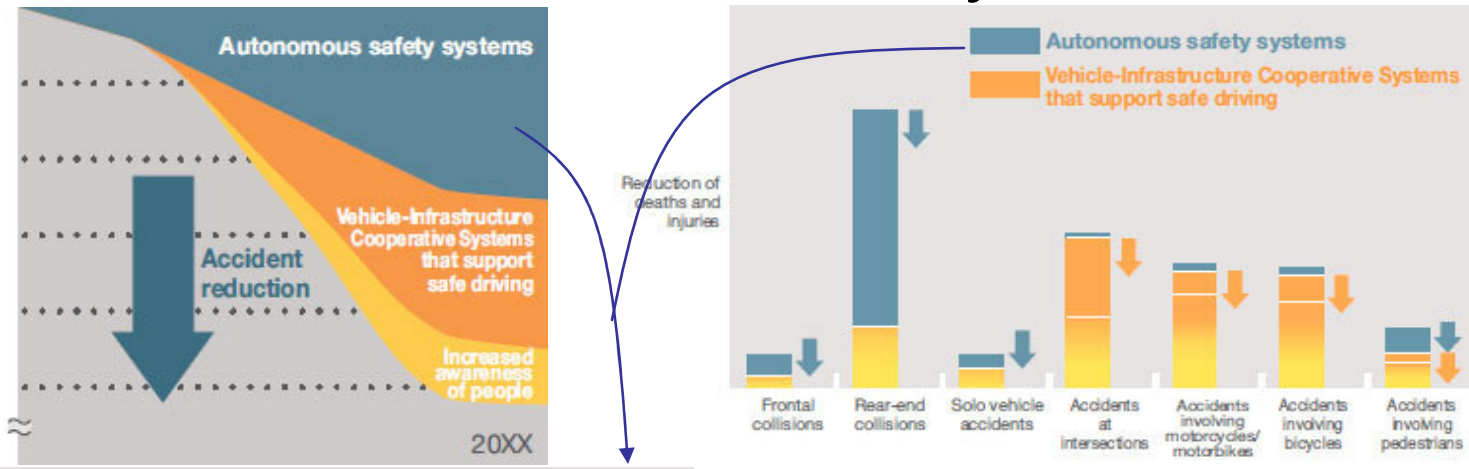


## Vehicle technologies

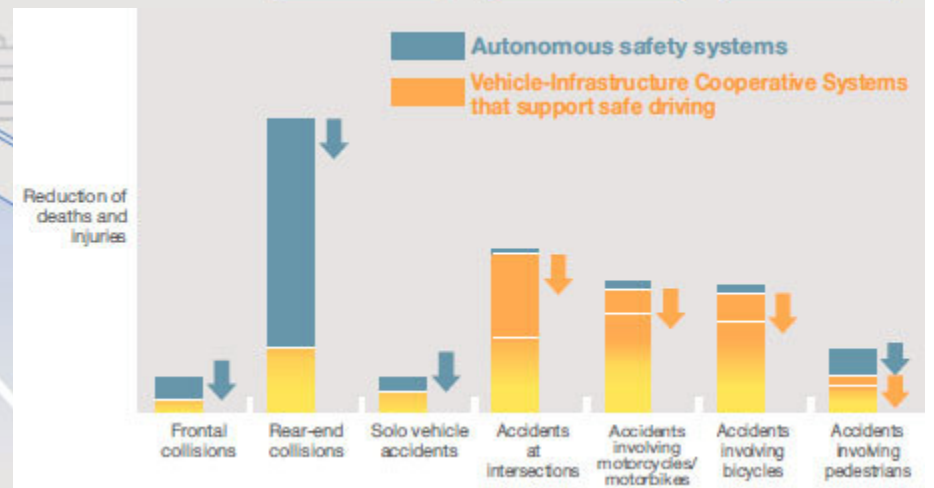
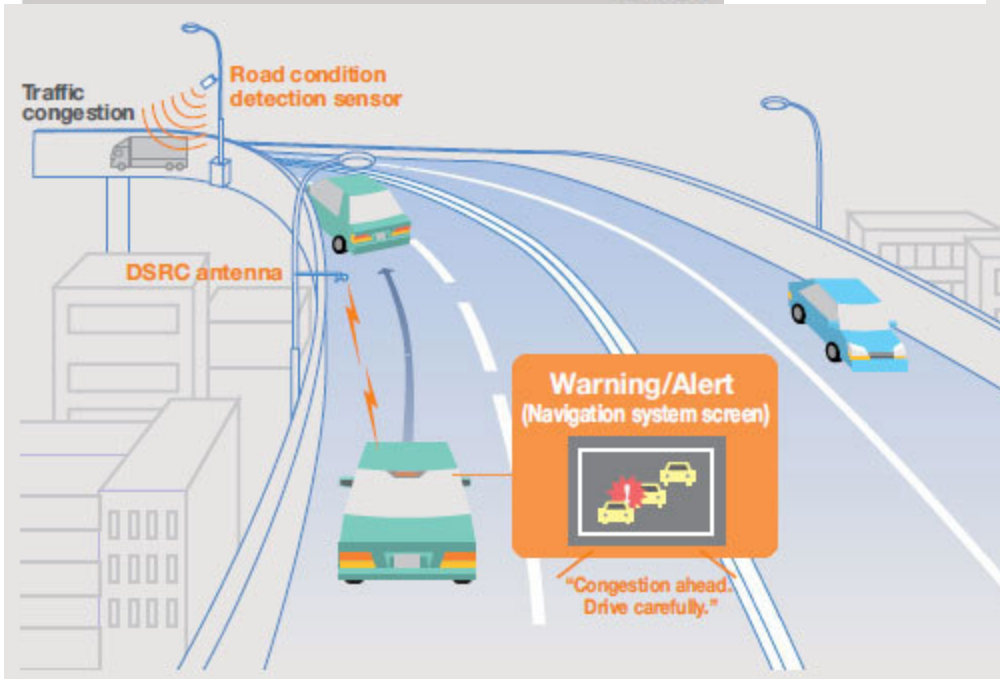
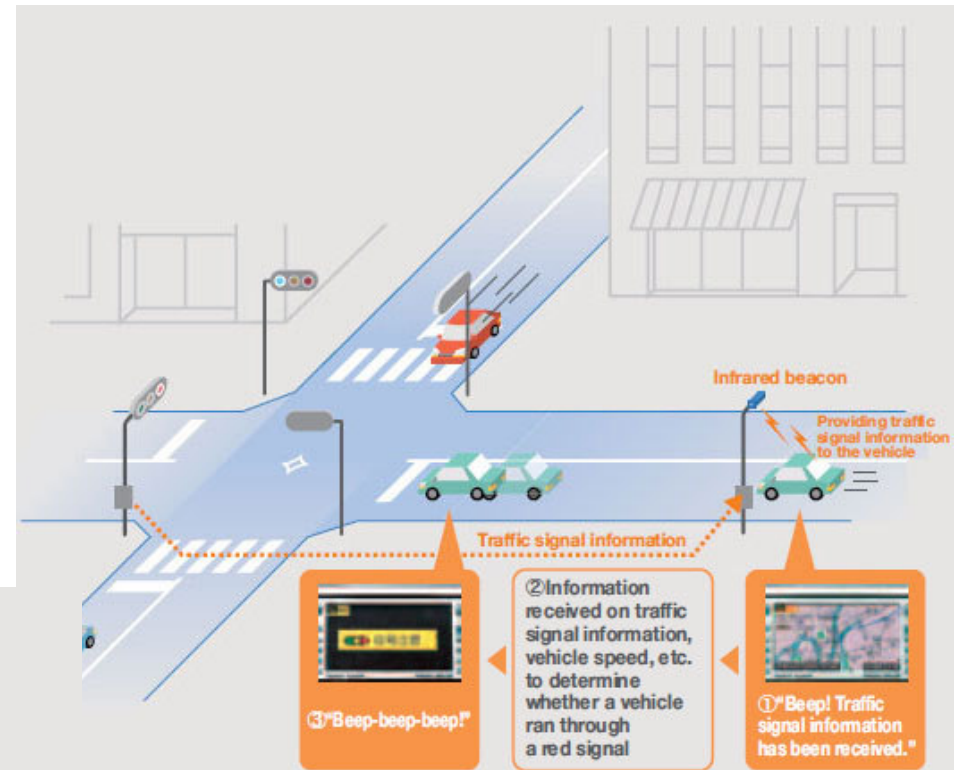
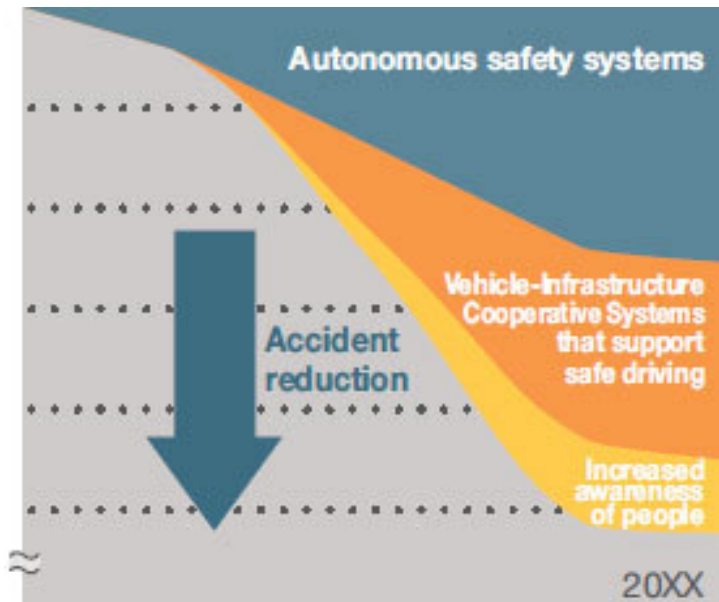
# Presentation Flow

1. Control, Electronics, Communication, and Embedded Software: Enabled Products and Features
2. Development Complexity and Mitigation
3. Future Development Challenge: Cyber-physical systems

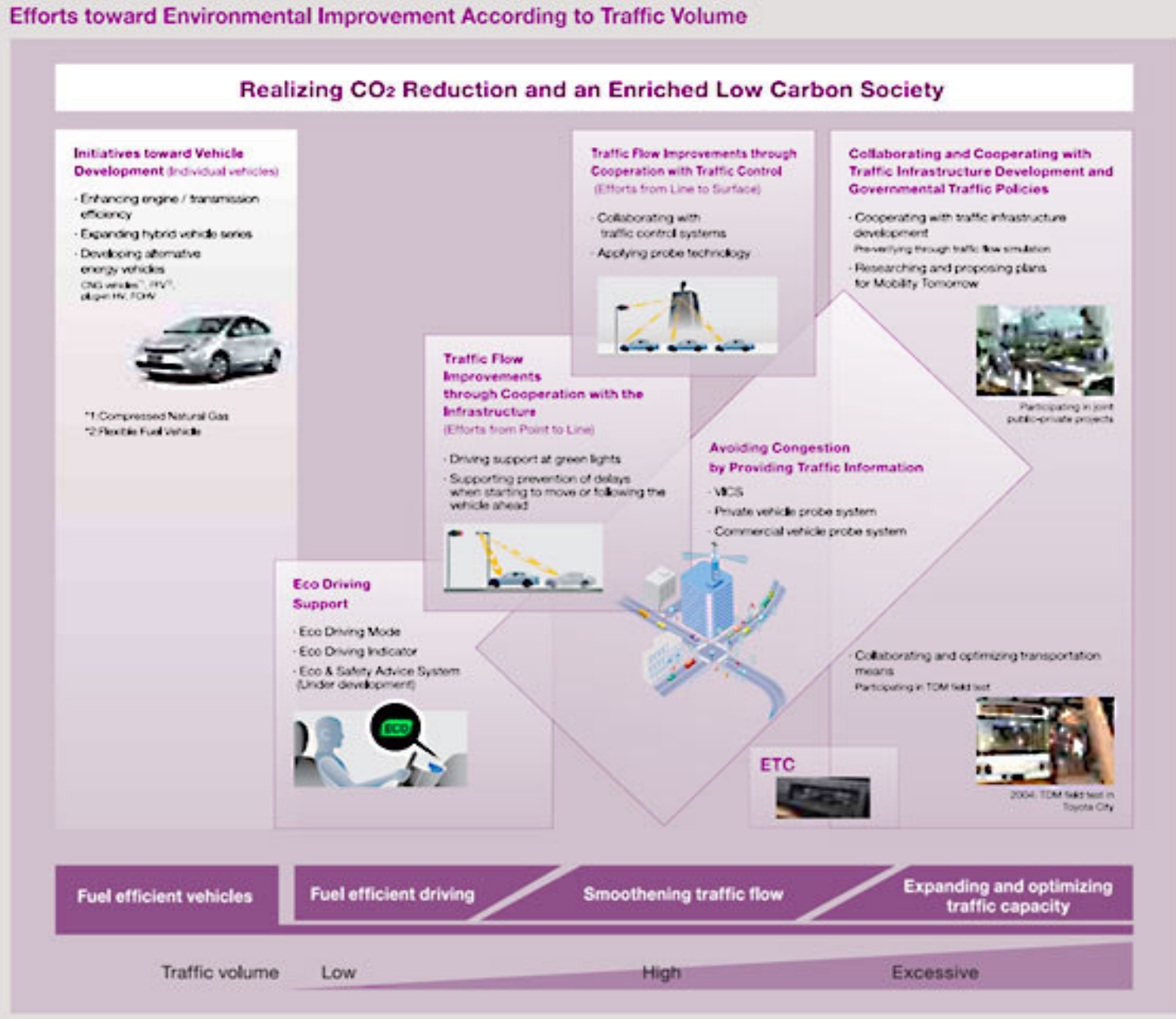
# Vehicle - Safety



# Vehicle – Infrastructure - Safety

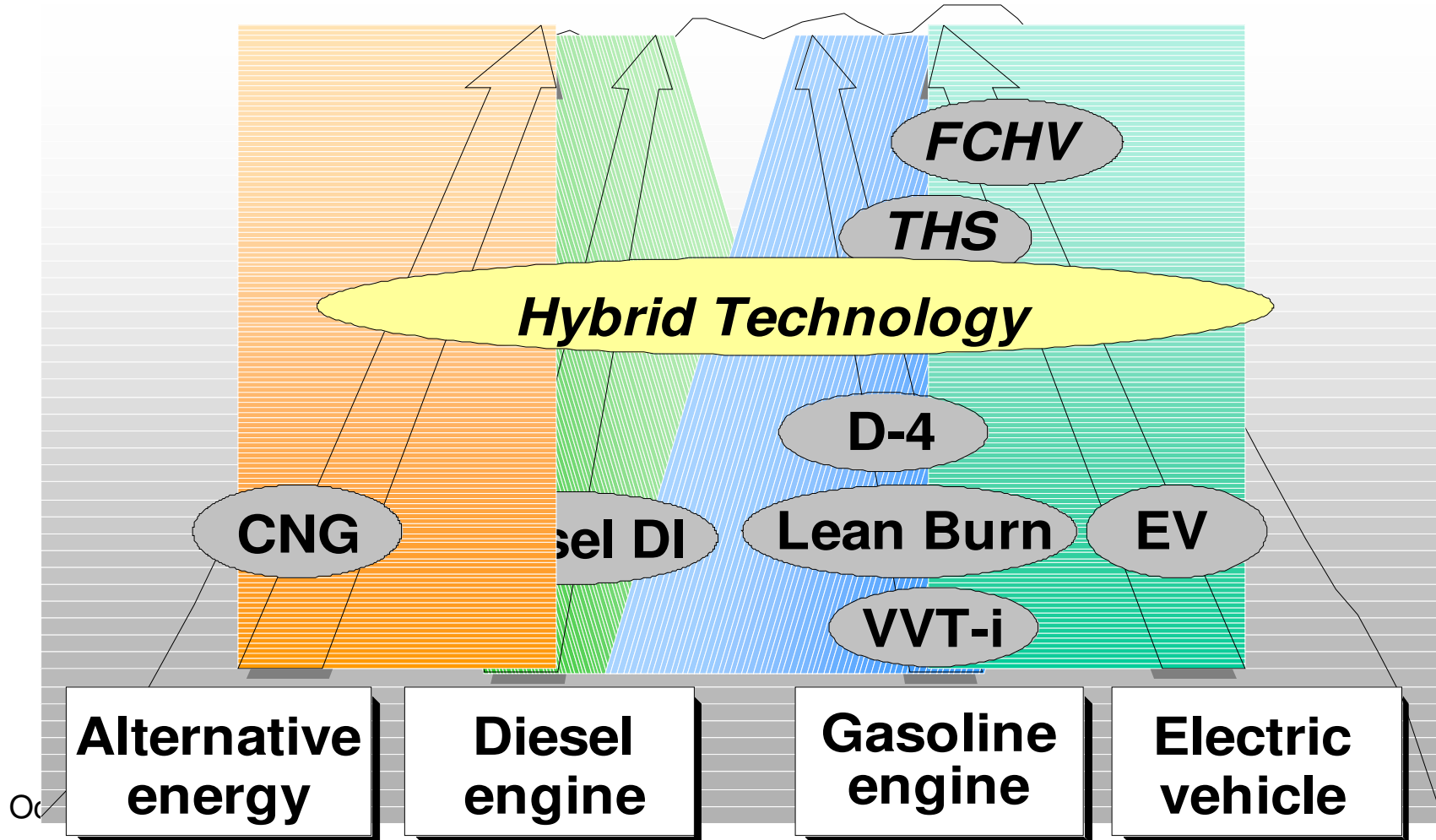


# Traffic flow management - Environment

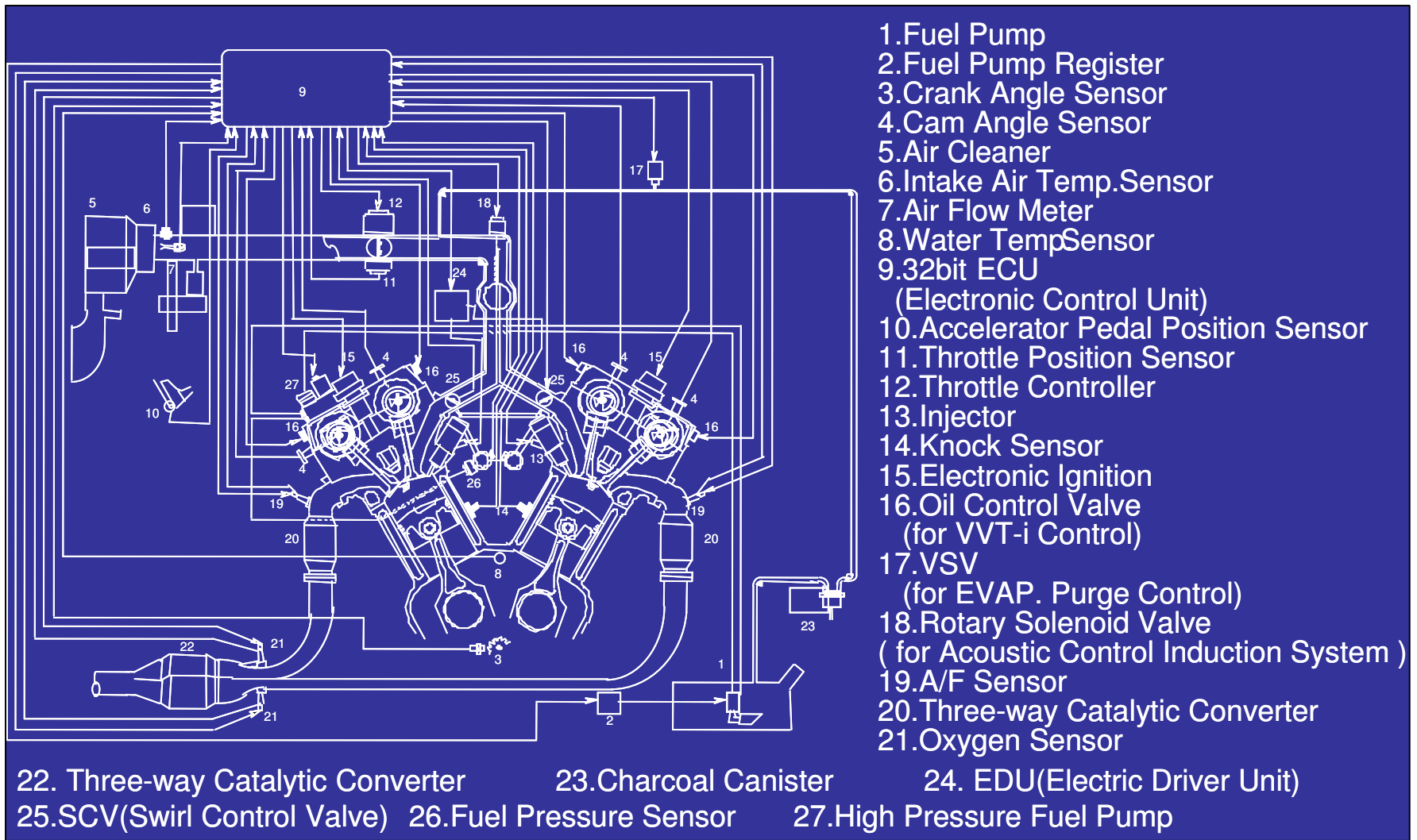


# Environment - Powertrains

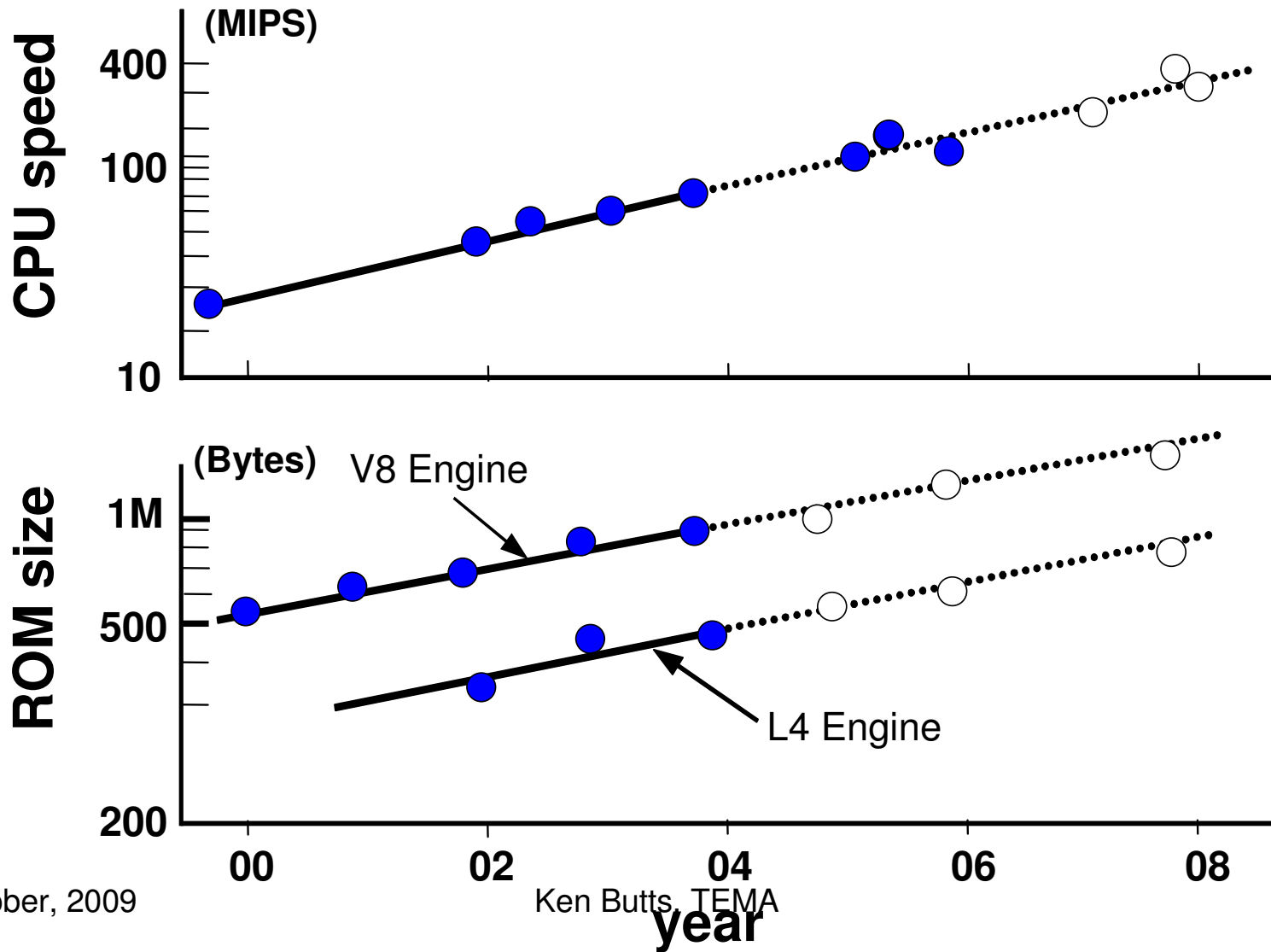
*Car of the future*



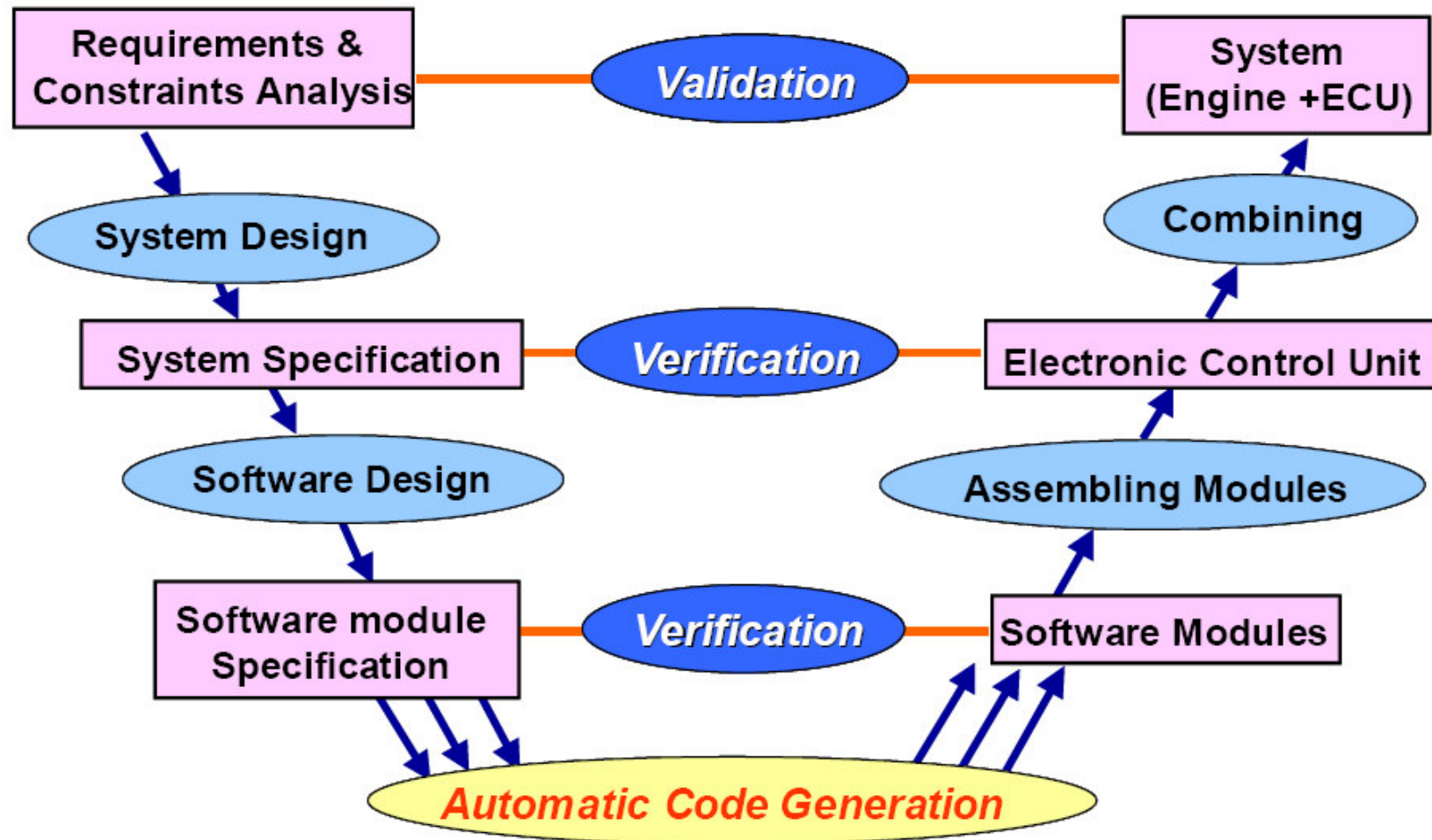
# Modern Gasoline engine control



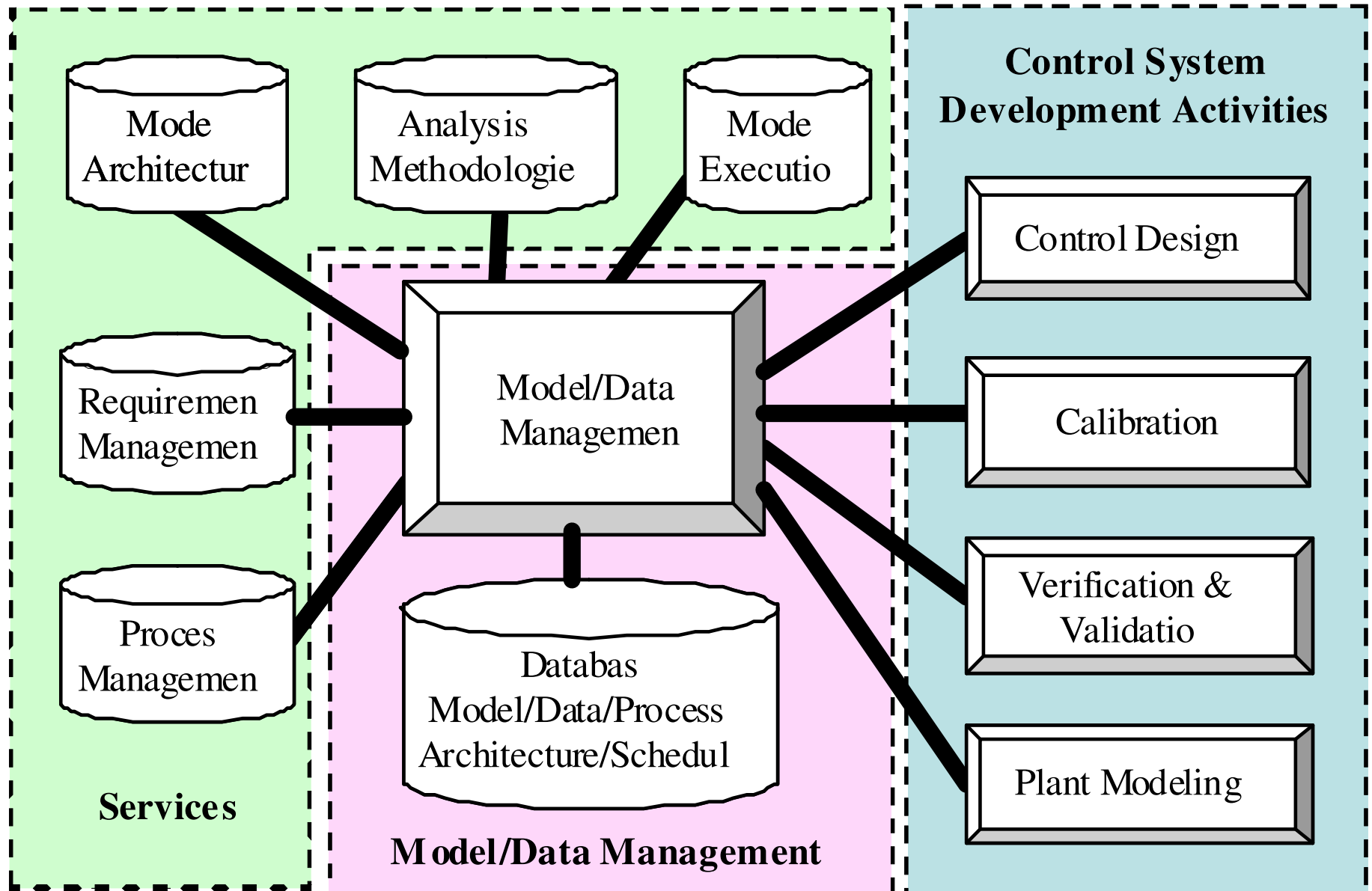
# Engine Controller Complexity



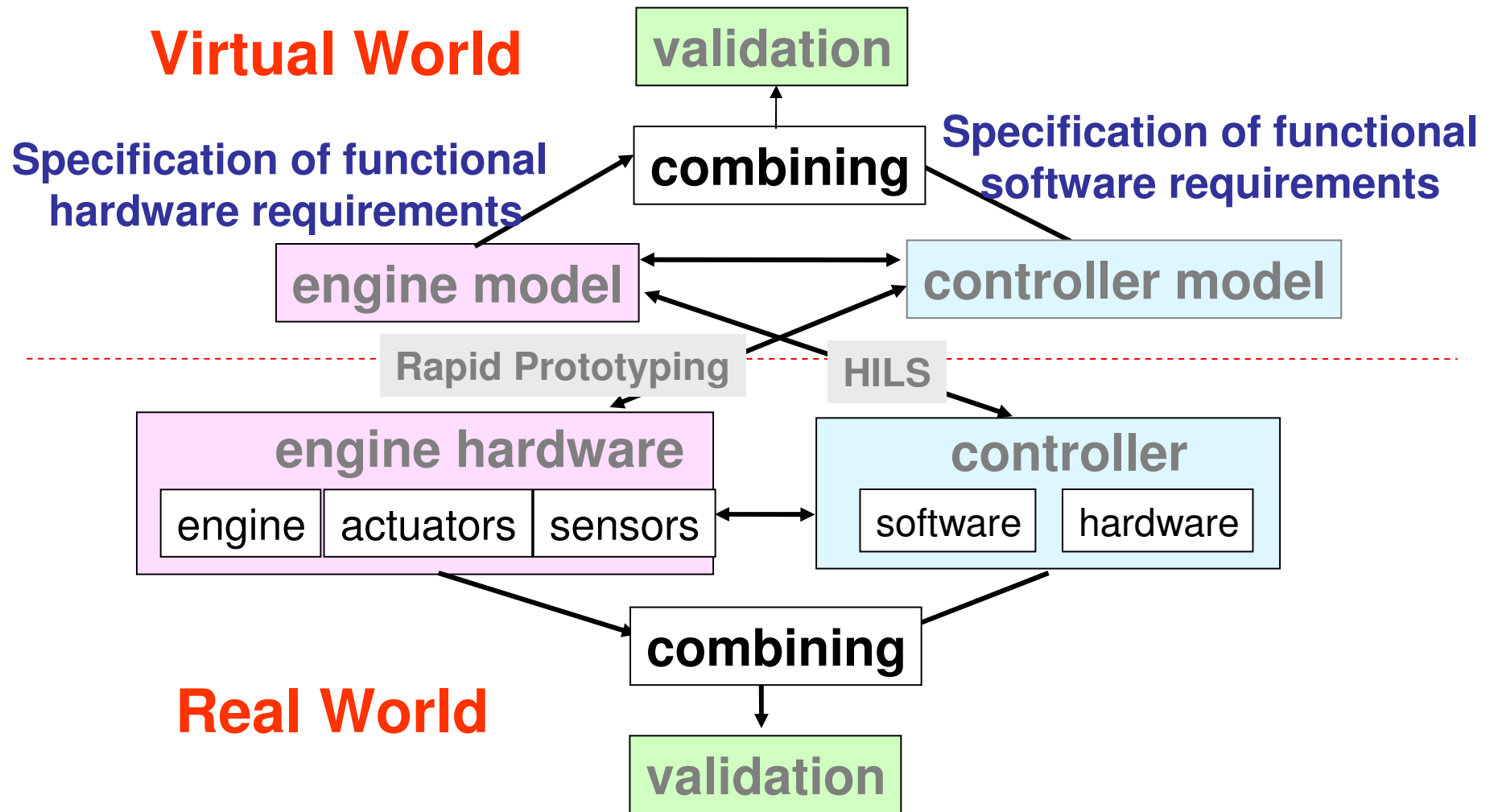
# Process View – Traditional ‘Systems V’



# Complexity Mitigation – Process and Information Management

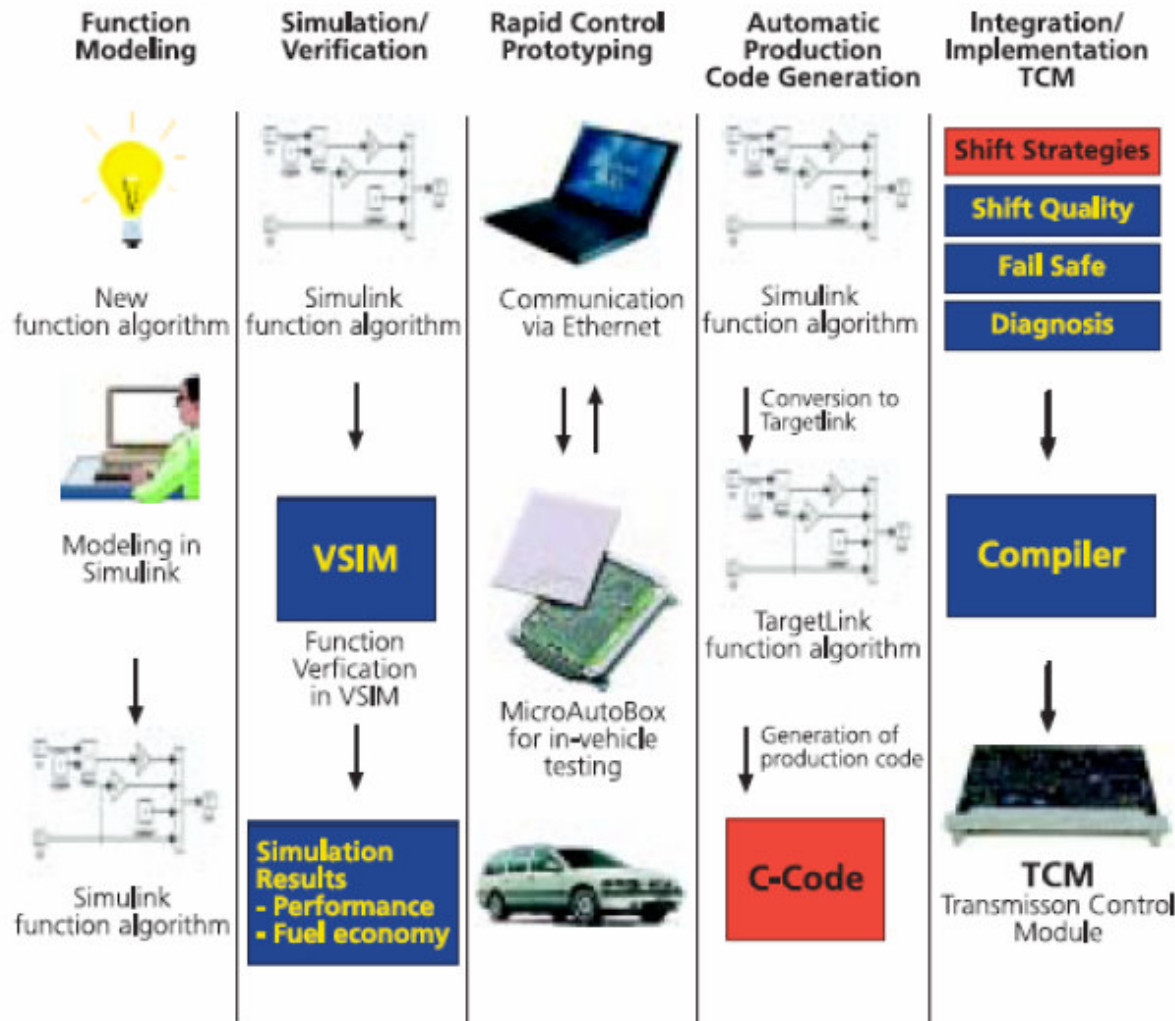


# Complexity Mitigation – Model-based Development



# Complexity Mitigation – Model-based Development

## Model-Based Function Development at Volvo Cars



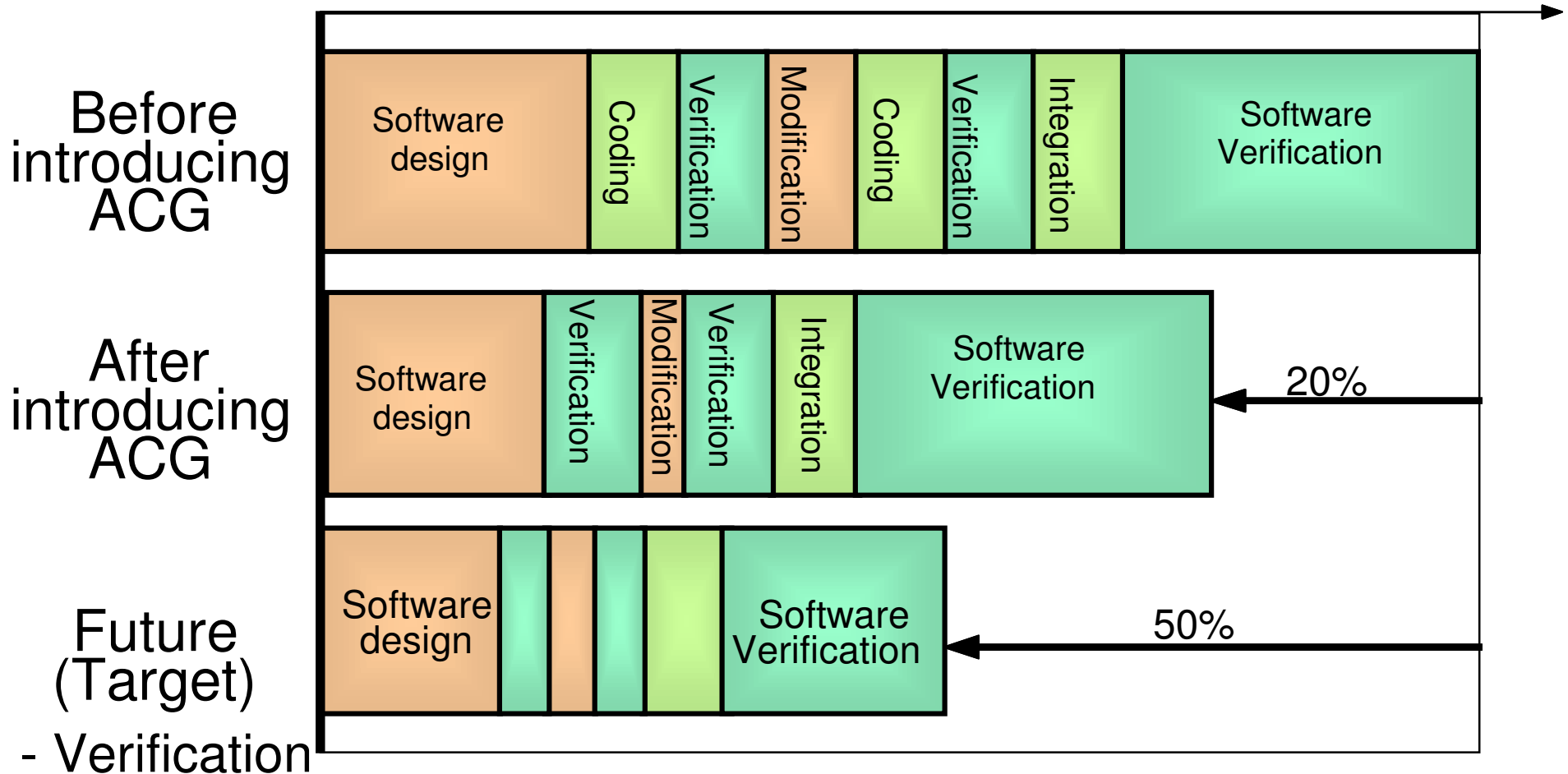
Goal:

Use models for

- requirements
- design
- verification
- test case generation
- modification
- documentation
- code generation
- run-time monitoring
- etc.

# Complexity Mitigation – Automatic Code Generation (ACG)

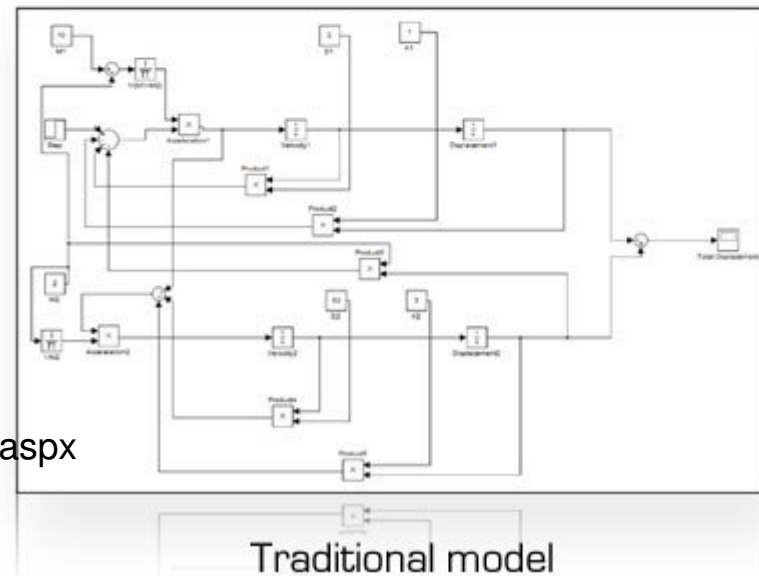
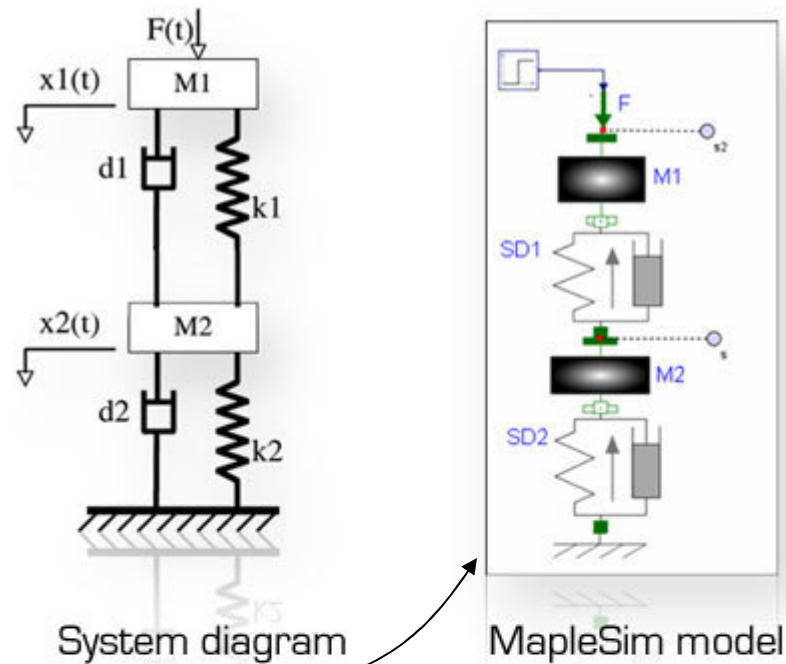
Development time



# Complexity Mitigation – Plant Modeling Productivity

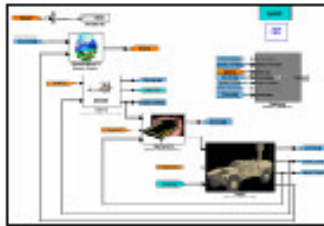
## Acausal, component based modeling\*

- Model diagrams map directly to the physical system
- Multi-domain modeling
- Symbolic system equations are generated automatically
- Multiple stages of symbolic model optimization



\*<http://www.maplesoft.com/products/maplesim/advantage.aspx>

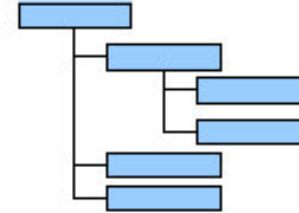
## Architecture Description Language



**Simulink:** Powertrain (MoVE) Architecture – Plant and Controls

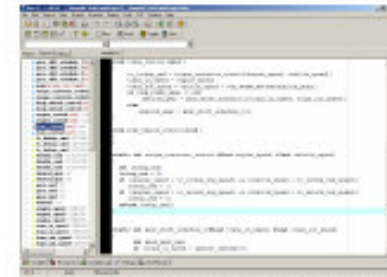


**Dymola:** Vehicle Modeling Architecture (VMA) – Plant and Controls



**PowerPoint:** Systems Level specification of Architecture – Plant and Controls

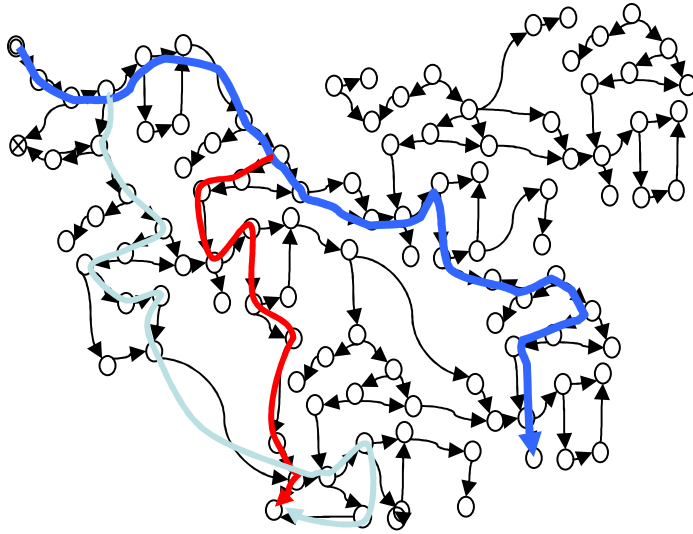
- Many possibilities for describing an architecture
  - AADL (Architecture Analysis and Design Language) - SAE standard
  - SysML – An OMG initiative
  - Modelica – A subset of Modelica could potentially be extended for this purpose
  - VHDL-AMS – A subset of VHDL-AMS could be potentially extended for this purpose
  - SADL (System ADL)
    - An immediate set of constructs that is being developed/used by Emmeskay for its tool IME
    - Will potentially be reconciled with one or more of the standard languages in the future



**C Code:** Legacy Controls Code

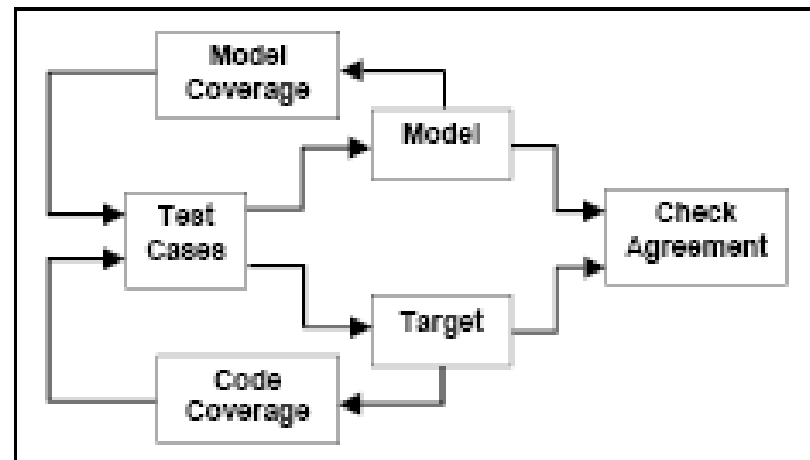
Models and Architectures in Other Tools, Domains, Languages (e.g. VHDL-AMS)

# Complexity Mitigation – Verification and Validation



**Automated test case generation**  
(path (model or code) structural coverage)

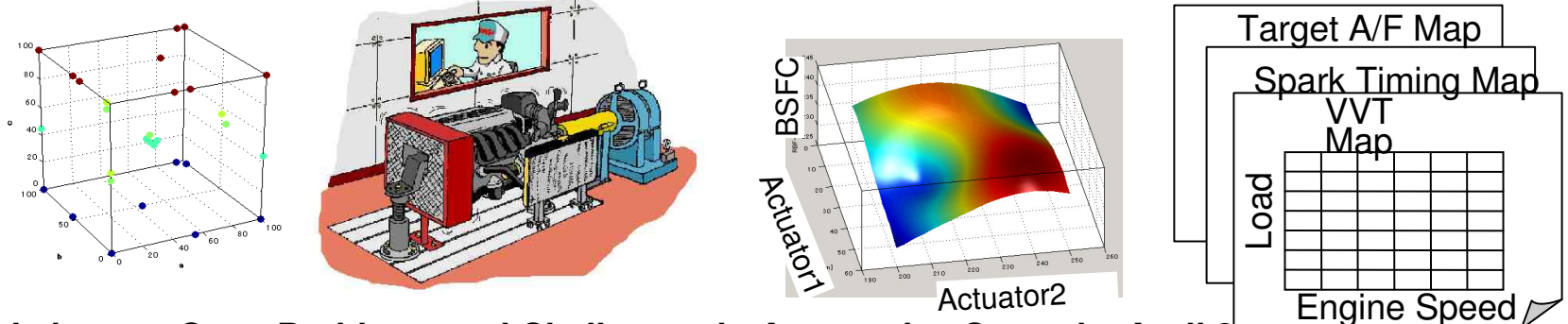
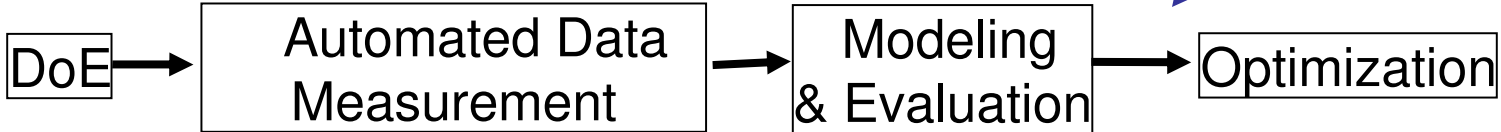
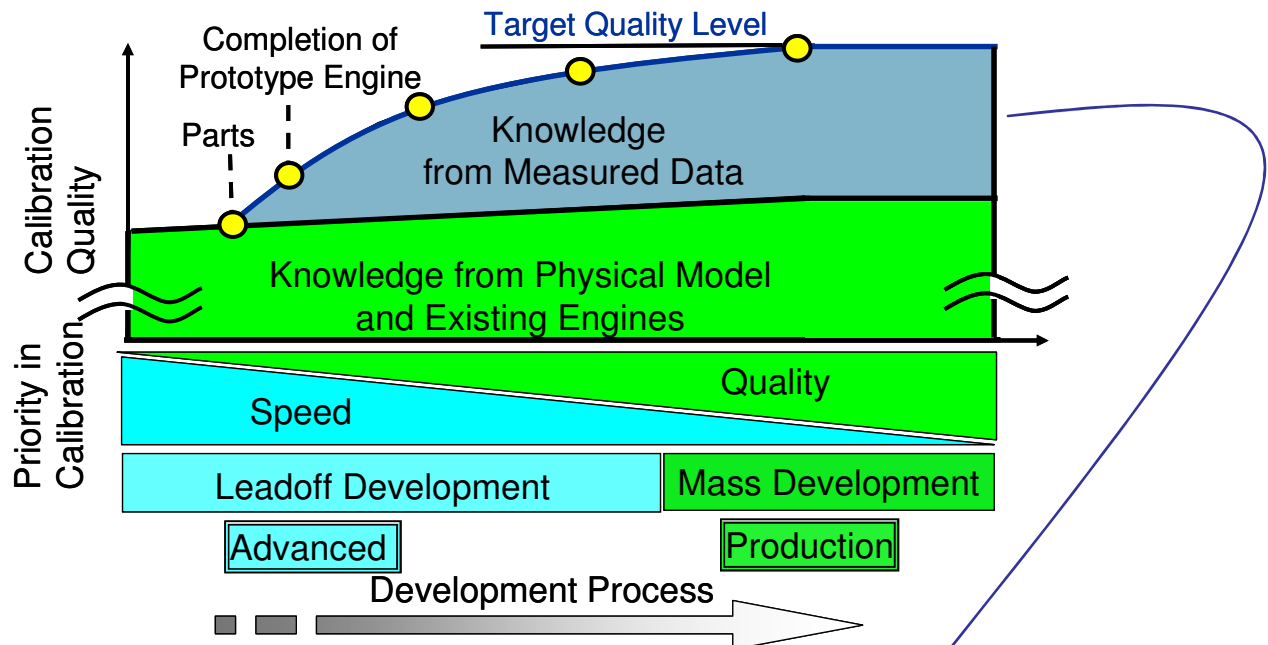
- **Style / Rules compliance checking**
- **Defect pattern detection**
- **Property checking**
- **Sensitivity / robustness evaluation**
- **Dependency analysis**
- **Model / code slicing**



**Model / Code equivalence checking\***

\* Coverage Analysis for Model Based Design Tools, William Aldrich, The MathWorks, Inc.

# Complexity Mitigation – Model-based Calibration



Workshop on Open Problems and Challenges in Automotive Control – April 2006

October, 2009

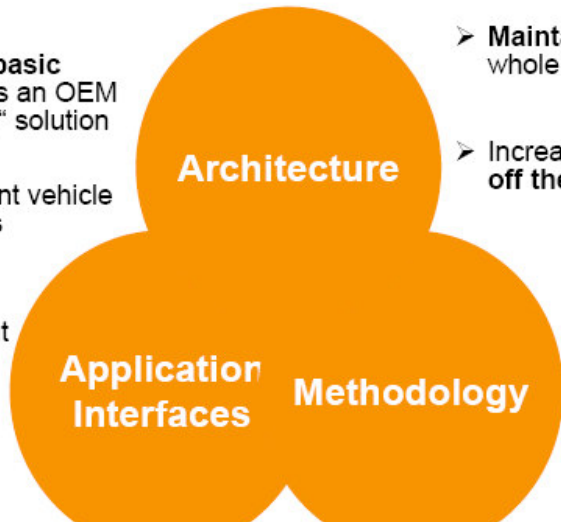
Ken Butts, TEMA

# Complexity Mitigation - AUTOSAR ECU standards\*

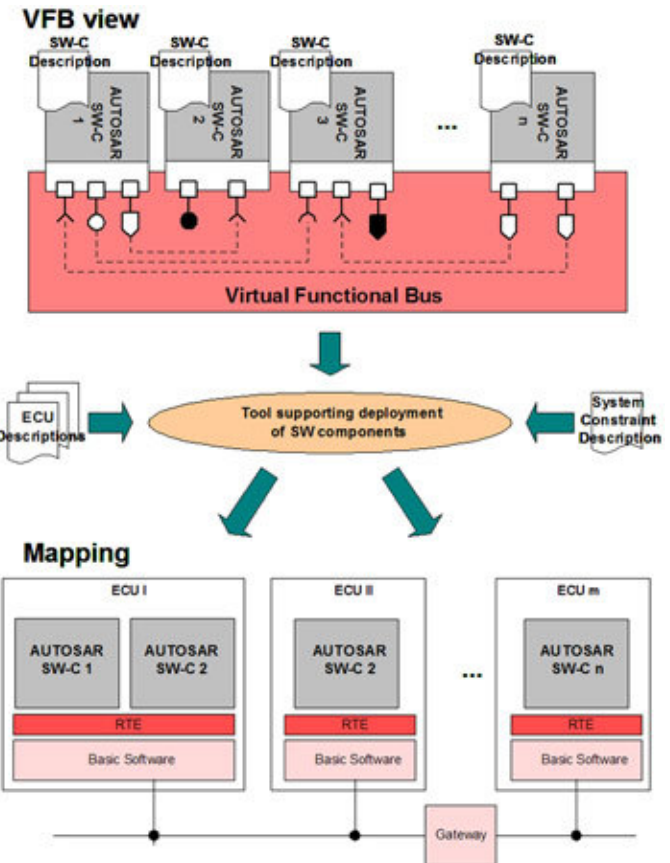


**AUTOSAR**  
Project Objectives and Main Working Topics

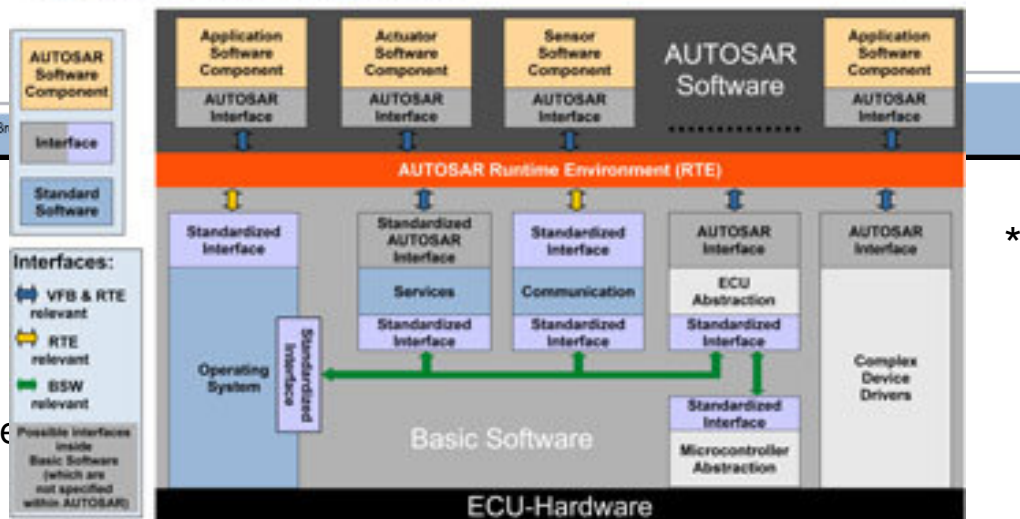
- Implementation and **standardization of basic system functions** as an OEM wide "Standard Core" solution
- **Scalability** to different vehicle and platform variants
- **Transferability of functions** throughout network
- **Integration of functional modules** from multiple suppliers



- **Maintainability** throughout the whole "Product Life Cycle"
- Increased use of "**Commercial off the shelf hardware**"
- **Software updates and upgrades** over vehicle lifetime
- Consideration of **availability and safety requirements**
- **Redundancy activation**



**Interfaces**  
Components and interfaces view (simplified)

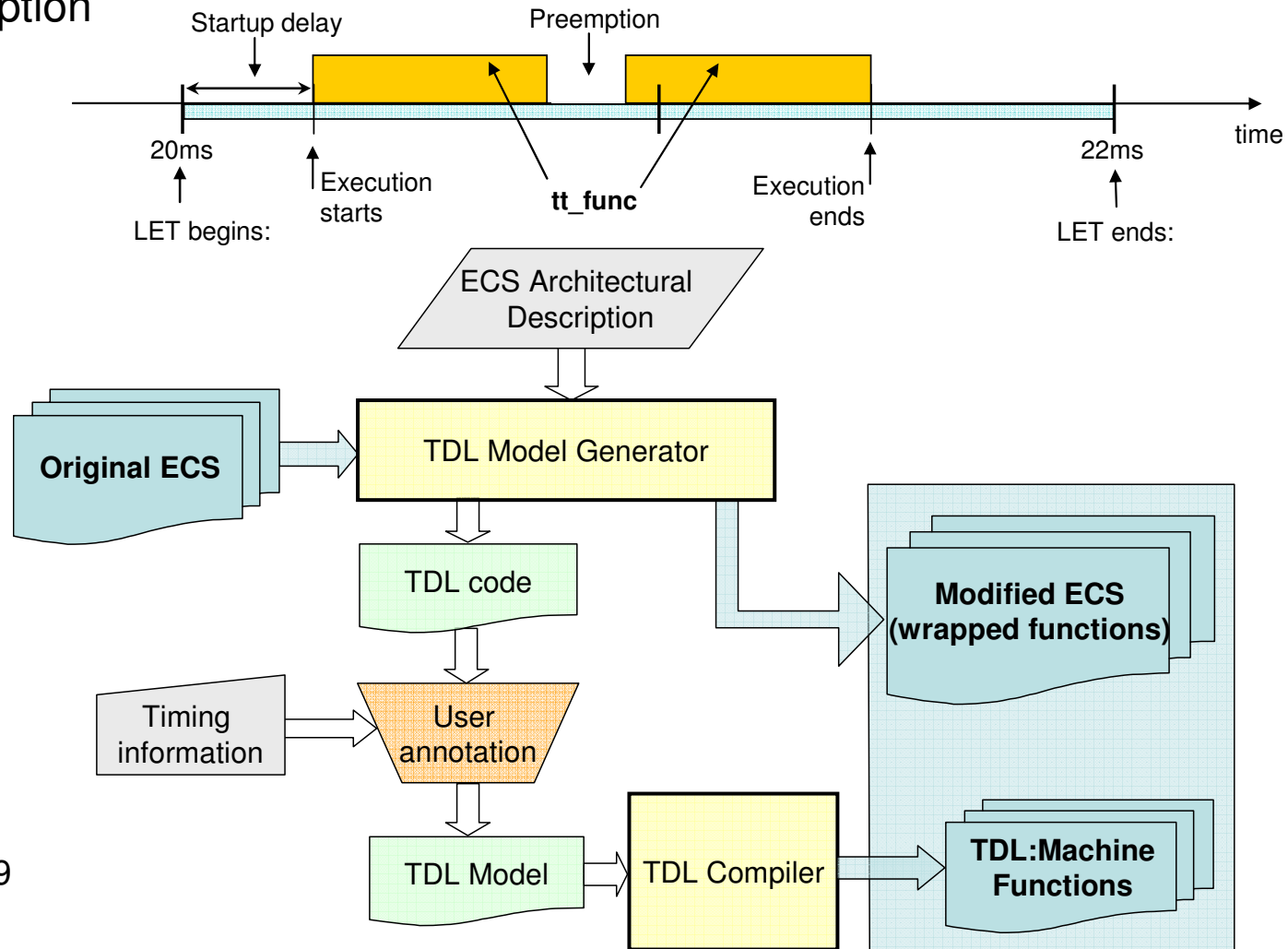


\*AUTOSAR Tutorial, Oct. 2008

# Complexity Mitigation

## Robust real-time software architecture

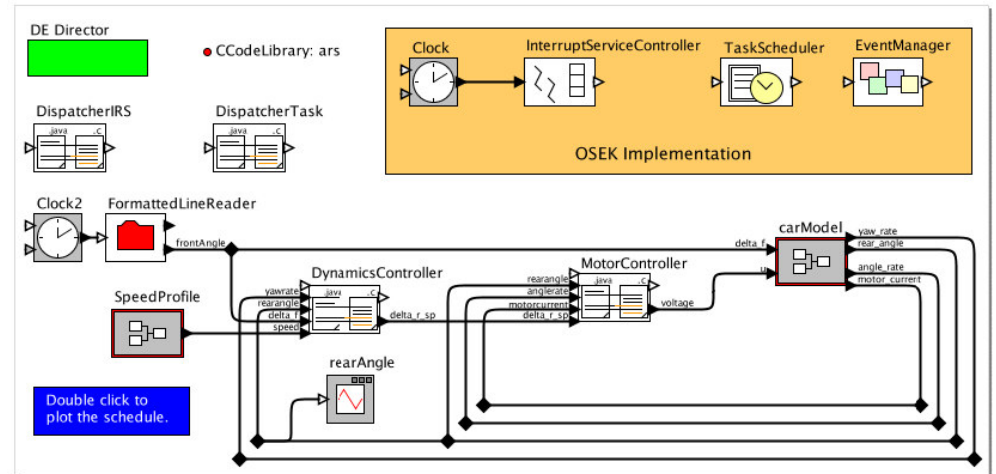
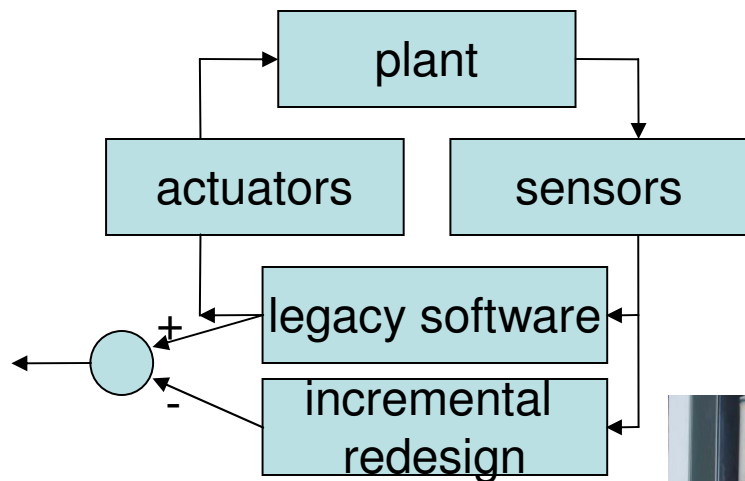
- Timing Definition Language (TDL) --> Robust real-time software behavior regarding:
  - Implementation architecture
  - Function reordering / redesign / addition / subtraction
  - Pre-emption



# Complexity Mitigation

## Code-based Legacy -- > Model-based Development

- Innovative Software Simulator to bring modeling and simulation capabilities to legacy design environments (CHES)
  - Incremental model-based development
  - Mixed code and model components → system level analysis
  - Real-time software behaviors: Software execution time
    - latency, jitter, schedulability
    - pre-emption
- ECU platform services model



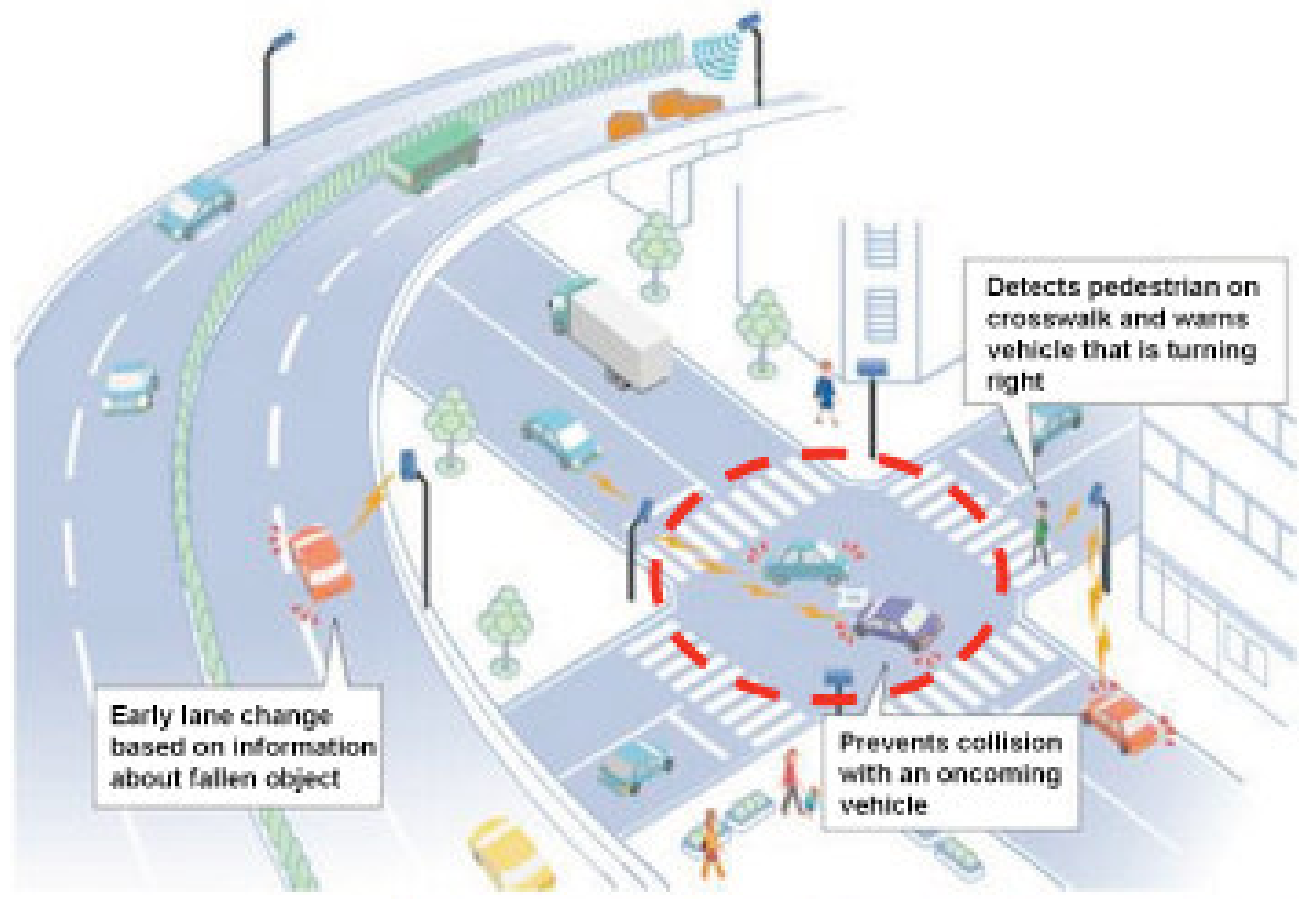
October, 2009



+ Daniel ...

# Methods Gap - Cyber-physical systems (e.g. collision avoidance)

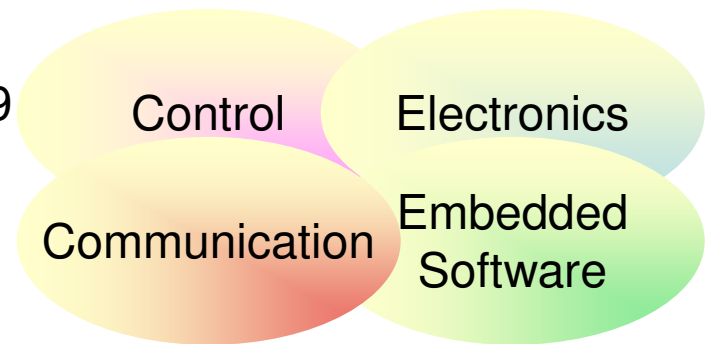
- Heterogeneous modeling – hybrid dynamics, wireless networking, dynamic agent scenarios
- Abstractions and refinements for synthesis and analysis – hierarchical systems structures
- Component composability and consistency – systems integration, rapid development
- Verification (within and across) design and implementation



# Take-aways

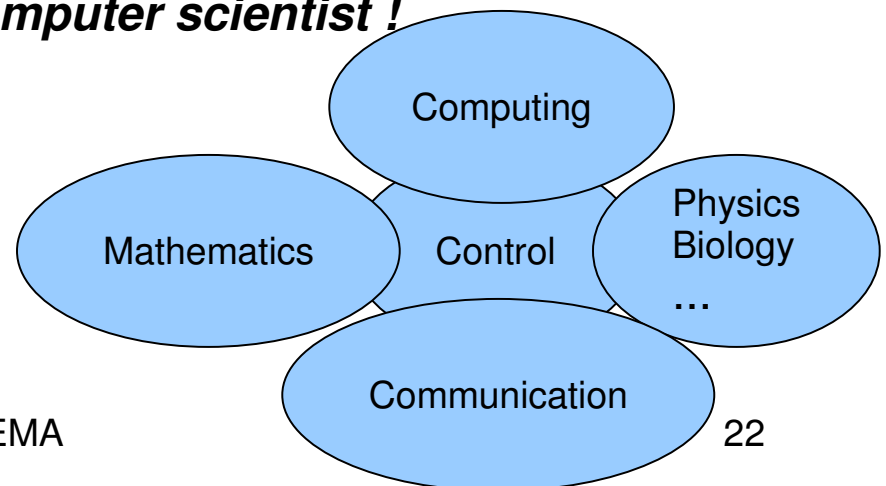
- Automotive industry is considering people, society, sustainable mobility, and infrastructure
- Automotive industry is increasingly exciting and dynamic due to Control, Electronics, Communication, and Embedded Software
- Cyber-physical systems are of great interest to society: Europe, Japan, U.S.
  - Aerospace
  - Light rail
  - Automotive
  - Smart grid
  - Biological and Medical systems
  - Process and Manufacturing
  - Environmental management ....

Ken Butts' view:  
October 15, 2009



→ ***What a great time to be an engineer / computer scientist !***

Karl Astrom's view:  
Impact of Control, October 19, 2009



October, 2009

Ken Butts, TEMA